Getting Started with ODTK

This exercise will give you hands-on experience with the ODTK user interface.

TIP: AGI recommends that you print out this document instead of attempting to use it on screen, since the PDF is optimized for printing rather than computer display. Also, if you display this document in an integrated HTML window, it will be displaced by some of the windows that you launch in the course of doing the exercise.

In the following pages, you will proceed step by step to set up and run a sequence of OD tasks:

- Initial Orbit Determination (IOD)
- Least Squares (LS)
- Optimal Orbit Determination (OOD) using a filter and each of two smoother algorithms (a VLS smoother and an RTS smoother)

In addition, you will become familiar with ODTK's reporting and graphing capabilities.

1 Access ODTK Help

Before starting this exercise, AGI recommends that you become familiar with the online ODTK Help system and briefly review the introductory chapters. Select ODTK Help from the Help menu:



AGI recommends that you review the "Using ODTK" section before starting the following tasks. In addition, you may want to reference the "OD Objects & Attributes" and "Reports & Graphs" sections as you run through the following tasks.

Before continuing, either minimize or close ODTK Help using the appropriate button on the ODTK Help Title Bar.

2 Set up some OD assets

To define the context for the OD tasks to follow, you will create an OD scenario and populate it with objects representing a tracking system, a satellite and a transponder. You will then practice using the OD user interface — in particular the **Object Browser** and the **Object Properties** window — to set properties for those objects.

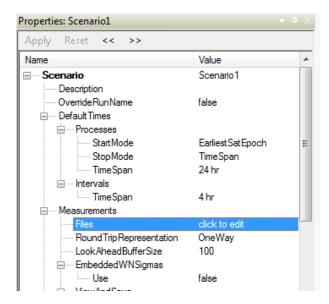
Create a scenario by clicking the scenario button and a satellite to the scenario by clicking the satellite object button.

NOTE: To access object buttons, click the downward pointing button on the Default toolbar, which displays other objects that you can attach to a selected object. You will use this same procedure to switch back and forth between the IOD and LS buttons when a satellite is highlighted (see below).

- 2. With the scenario highlighted in the browser, select Import \rightarrow Import Object from the File menu.
- 3. In the lower-right corner of the file selection dialog box, use the drop-down menu to set the file search type to TrackingSystem Files (*.tso). Open the file Baseline.tso, which is located at <ODTK Install>\ODTK\AppData\Databases\TrackingSystems\Baseline.tso; this loads a tracking system.
- 4. Highlight the satellite and click ▼ on the Default toolbar, and select Transponder (2). The Browser should appear as follows at this stage:



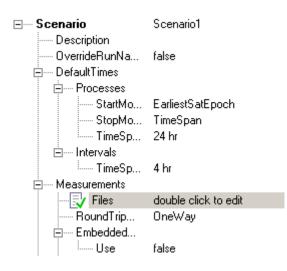
5. Double-click the scenario in the Browser to expose its properties. Select the Measurements → Files property:



6. Click where it says "click to edit." In the Scenarios.Measurements.Files dialog box that appears, click the Add button.

E Scenario.Measurements.Files	×
Enabled & Filename	AliasMapping Add
true C:\Program Files\AGI\ODTK 7\ODTK\UserData\Trackin	gData\V1001.geosc Remove
	Remove All
<	>
	OK Cancel Help

7. Double-click the Filename field and load the file V1001.geosc, which is located at <ODTK install>\ODTK\UserData\TrackingData\. Click OK to save this and close the dialog box; the Object Properties window will be marked to indicate that you changed a property:



8. Apply the property change by clicking Apply in the upper-left corner of the Object Properties window.

NOTE: From this point forward in this exercise, when you are instructed to "Apply the property change(s)," it means to follow the above procedure.

TIP: If you change your mind about changes you made in the Object Properties window before clicking Apply, click Reset to restore the values of the affected properties to their values prior to the changes.

- 9. Open the Object Properties window for the satellite and, under Orbit State, change its Epoch to 1 Jun 2015 12:00:00.000 UTCG.
- 10. Then scroll down to the OrbitUncertainty attributes and make the following changes:
 - R_sigma: 500 m
 - I_sigma: 10000 m
 - C_sigma: 100 m
 - Rdot_sigma: 0.6 m/s
 - Idot_sigma: 0.4 m/s
 - Cdot_sigma: 0.2 m/s

Object Properties: Satellite1		
Apply Reset << >>		
Name	Value	*
Satellite	Satellite1	
Description		
EstimateOrbit	true	
🗄 ····· Orbit State	Cartesian	
······ OrbitClass	LEO	
Physical Properties		
🗄 ····· Attitude		Ξ
······ MinGrazingAlt	100 km	
Measurement Process		
i ForceModel		
PropagatorControls		
EphemerisGeneration		
Orbit Uncertainty		
······ R_sigma	500 m	-
······ I_sigma	10000 m	
C_sigma	100 m	
Rdot_sigma	0.6 m*sec^-1	
······ Idot_sigma	0.4 m*sec^-1	
······ Cdot_sigma	0.2 m*sec^-1	
······ RI_correlation	0	
····· RC_correlation	0	
······ RRdot_correlation	0	
····· Rldot_correlation	0	
RCdot correlation	0	Ŧ

11. Click Apply. Click the 🗐 (Preview Measurements) icon and observe that the results of the loading operation are displayed in the Message Viewer window:

Туре	Message	Date/Time /	Filename	Line #
Information	Tracking File preview started	05-10-2023 01:57:24 PM	AgODObservationManager.cpp	2646
Information	File 1: # Meas = 2524 { 01 Jun 2015	05-10-2023 01:57:24 PM	AgODObservationManager.cpp	2954
Information	All Files: # Meas = 2524 { 01 Jun 201	05-10-2023 01:57:24 PM	AgODObservationManager.cpp	2980
Information	The Following Trackers are in the Tracki	05-10-2023 01:57:24 PM	AgODObservationManager.cpp	3007
Information	The Following Satellites are in the Tracki	05-10-2023 01:57:24 PM	AgODObservationManager.cpp	3041
Information	Tracking File preview completed	05-10-2023 01:57:24 PM	AgODObservationManager.cpp	3108

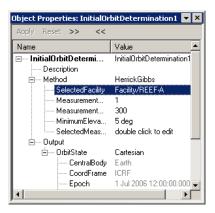
All Messages (Errors) Warnings) Infos /

NOTE: It sometimes takes several seconds for ODTK to carry out an action and display the results in the Message Viewer window.

3 Perform Some OD tasks

3.1 Initial Orbit Determination (IOD)

- 1. With the satellite highlighted, click the downward pointing ▼ button on the Default toolbar and select the 📴 button to add an Initial Orbit Determination object.
- 2. Open the IOD object's properties, and make certain that Method is set to HerrickGibbs, and that the SelectedFacility is REEF-A. Confirm any changes that you had to make.



- 3. Click the SelectedMeasurements field, and, in the List window that appears, click the Add button to display the Add Item(s) window.
- 4. Select data points 0000, 0020, and 0040.

TIP: To multi-select items, hold down the CTRL button and click the left mouse button on each desired item.

InitialO	phitDetermination.Method.SelectedMeasure	ments	×
	Add Item(s)	23	
Measure	0000 01 Jun 2015 14:13:00.000 1403 228	5.743	Add
	0010 01 Jun 2015 14:13:10.000 1351.617	6.356	Remove
	0020 01 Jun 2015 14:13:20.000 1301.821	7.032	
	0030 01 Jun 2015 14:13:30.000 1254.065 0040 01 Jun 2015 14:13:40.000 1208 587	7.745	Remove All
	0050 01 Jun 2015 14:13:50.000 1165.672	9.111	
	0060 01 Jun 2015 14:14:00.000 1125.603 0070 01 Jun 2015 14:14:10.000 1088.723	9.846	
		11.141	
	0090 01 Jun 2015 14:14:30.000 1025.848	11.695	
	0100 01 Jun 2015 14:14:40.000 1000.560 0110 01 Jun 2015 14:14:50.000 979.808	12.284	
	0120 01 Jun 2015 14:15:00.000 963.890	12.995	Help
<u> </u>	0130 01 lup 2015 14-15-10 000 953 062	12 222	

- 5. Close the Add Item(s) and List windows by clicking OK and apply the property changes.
- 6. Highlight the IOD in the Object Browser and click the 🕨 (Run) button on the toolbar to run it. Note the changes in the Object Properties window. The Message Viewer window will indicate when IOD is finished.
- Now transfer the results of the IOD to the initial state of the satellite. With the IOD still highlighted, click the (Transfer to Satellite) icon and note the confirmation in the Message Viewer window.

3.2 Least Squares (LS)

Highlight the satellite again and attach a Least Squares object using the *G* icon. Double-click the LS object to expose its properties, and click the Run button to run Least

Squares. Observe the changes in the Object Properties window and in the Message Viewer window.

2. Again, click the K (Transfer to Satellite) button to transfer the LS results to the satellite's initial state, again noting the confirmation in the Message Viewer window.

3.3 Optimal Orbit Determination (OOD) with the Filter

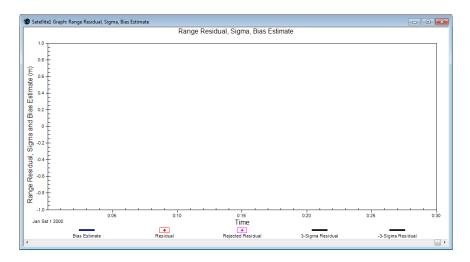
- 1. Highlight the scenario in the Browser and click the *icon* to insert a filter.
- 2. Double-click the filter object to expose its properties.
- 3. Find MeasTypes and click the "click-to-edit" area; the Filter.MeasTypes dialog box appears.
- 4. Click the Add button, select Range and Doppler from the Add Item(s) list, and click OK twice. Apply the property changes.

Filter.MeasTypes	×
Measurement Type Range Doppler	Add Remove Remove All
OK Cancel	Help

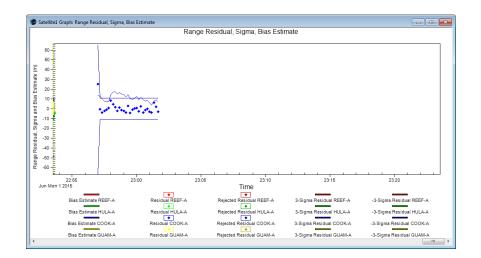
- 5. From the View menu, select Dynamic Product Selector.
- 6. In the Dynamic Reports dialog box, make certain that Report is selected as the Dynamic Display format, that Satellite is selected as the Object Type, that all Styles except "Instant Maneuver Estimate Update" are selected, and that the satellite is highlighted in the Satellites column.
- 7. Click the Create button.

Ø Dynamic Reports		- • •
Dynamic Display	Object Type Satellite	○ Facility
Styles Instant Maneuver Estimate Update Measurement Bias Update Measurement Update Time Update	Satellites Satellite1 Create Help	

- 8. Click the lower Dynamic Reports tab to return to the Dynamic Product Selector.
- 9. Select Graph as the Dynamic Display format and Satellite as the ObjectType. Select Dyn_Range_Residual in the Styles column, and make certain that the satellite is high-lighted in the Satellites column.
- 10. Click the Create button to display the following window:



11. Now, with the filter highlighted in the Browser, run it. Monitor the OOD process via the T (Filter Time Update), M (Filter Measurement Update), and Trackers windows. Selected data will appear dynamically in the graph window:



The Message Viewer window will indicate when filtering is done.

NOTE: Depending on the number of measurements involved, the filtering process can take a while.

3.4 OOD with the Variable Lag Smoother (VLS)

ODTK has two smoothing algorithms. One is a forward-running variable time lag sequential smoother that runs with the filter and is a child of the filter object. This algorithm is called the Variable Lag Smoother (VLS). You enable it by setting the Filter \rightarrow ProcessControl \rightarrow EnableVLS property to true and then inserting a VLS object under the Filter. The second is a backward-running Rauch-Tung-Striebel (RTS) sequential smoother, which runs after the filter is completed. It requires the filter to provide data to the smoother via a set of "*.rough" file(s). You enable this smoother by inserting a Smoother object to the Scenario.

- 1. To employ the VLS, first double-click the filter in the Object Browser to expose its properties.
- 2. Verify that the Filter \rightarrow ProcessControl \rightarrow EnableVLS property is set to true.
- 3. With the filter still highlighted, click the downward pointing button on the Default toolbar and select the button to insert a VLS.
- 4. Double-click the VLS object to expose its properties. Set the VLS → Output → FilterDifferencing → Generate property to true.
- 5. Highlight the filter in the Object Browser and run it by clicking the ♥ (Run) button in the ODTK toolbar. ODTK generates a *.filrun file, a *.smtrun file, and a *.difrun file for use by the Static Product Builder Reporting and Graphing interface.

3.5 OOD with the Rauch-Tung-Striebel (RTS) Smoother

- 1. To employ the RTS, first highlight the filter in the Browser and double-click to expose its properties. Set the Filter \rightarrow ProcessControl \rightarrow EnableVLS property to false.
- 2. Set the Filter \rightarrow Output \rightarrow SmootherData \rightarrow Generate property to true. This exposes the Filter \rightarrow Output \rightarrow SmootherData \rightarrow Filename property. This property is the name of the *.rough file that ODTK uses to pass data from the filter to the RTS smoother.
- 3. Highlight the filter in the Browser and run it by clicking the 🚩 (Run) button in the ODTK toolbar. This will create a *.filrun file and a *.rough file.
- 4. Highlight the scenario in the Object Browser, click the downward pointing ***** button on the Default toolbar, and select the 👯 button to insert a smoother object.

- 5. Double-click the smoother object to expose its properties.
- 6. Go to Smoother \rightarrow Input \rightarrow Files and click the "click to edit" area; the Smoother.Input.Files dialog box appears.
- 7. Click the Add button and click under Filename. Load the *.rough file that was generated by the filter (given by the Filter \rightarrow Output \rightarrow SmootherData \rightarrow Filename property) and click OK to close the dialog box.
- 8. Set the Smoother \rightarrow Output \rightarrow FilterDifferencingControls \rightarrow Generate property to true.
- 9. Highlight the smoother in the Browser and run it by clicking the 🕨 (Run) button in the ODTK toolbar. ODTK will generate a *.smtrun file and a *.difrun file for use by the Static Product Builder Reporting and Graphing interface.

Reporting and graphing features 4

You gained some experience above with dynamic reports and graphs that continuously update during a filter run. Here you will create a static report and graph on the basis of the output of a completed filter run.

Note1: The activities in this section require the filter output that is generated by the activities in the preceding sections. If you have not yet completed those activities, you must do so before proceeding.

NOTE2: The technique to generate static report and graphs for a completed smoother run is similar. The smoother run file will have the extension ".smtrun". However, some reports and graphs (like residuals and histograms) that apply to the filter do not apply to the smoother since neither smoother type does measurement modeling. Also, there are no dynamic graphs associated with the smoother.

4.1 Static reports

The following activity will give you a sample of ODTK's powerful reporting capabilities.

1. From the View menu, select the Static Product Builder.

- 2. Click the Inputs tab.
- 3. In the Data Source area, click the Add button
- 4. Click where indicated in the Filename field and load the filter run (*.filrun) file that you created above.

t 6 6 6 9 7 7 8 9	Outputs Inputs				
Products	Data Source				
P Data Product	Enabled	Objects	Filename		Add
	true	click to edit	C:\Users\motsay\Documents\ODTK 7\DataArchive\Scenario1.filrun		Remove
	<			> Re	emove All
	 Satellit Tracke Trackii Trackii Transp 	er Name	×		
* 20 6 6 ?	Use Tim	e Period	UTCC IIII Stop 2 Jun 2015 08:15:00.000 UTCC IIII		

- 5. Click the Outputs tab and select the Residuals with Bias by Tracker report style from the Products Styles list.
- 6. Click on the default name for the report (on the left side of the window) and rename it:

	he selected Data Product.		
* 6 6 6 9 7 8 6	Outputs Inputs		
	Product Styles (Graphs and Reports)		
Products ≌ Data Product	Residuals by Elevation Angle Residuals by Grazing Altitude Residuals by Range Residuals by Range Rate Residuals with Bias Residuals with Bias By Satellite Residuals with Bias By Stard Residuals with Bias By Tracker Residuals with Bias By Tracker Retoreflector Delay Satellite Classical Elements Uncertainties (a e) Altitude Reports residuals with +/- three-signa b	Satellite Classical Elements Uncertaintie Satellite Consistency Satellite Consistency Summary Satellite Consistency Summary Satellite Summary Sim Atmosphere Density Estimate Sim Measurement Noise Sim SRP Estimate Sim SRP Estimate Sim Transponder Bias Sim Constant Statellite Sim Statellite Statellite Sim Statellite Statellite Sim Statellite Constant Sim St	
	Location: C:\Program Files\AGI\ODTK 7\ODTK\App	pData\Styles\Static\Residuals_with_Bias_By_Track	er.pyrpt
	Edit Add Graph -		Edit Tabs
	Display Product		

7. Now click the 🖾 (Run Selected) icon to launch the Report Viewer window. As you can see, the report lists measurements by facility and, per your specifications, is limited to range and Doppler measurements:

Report Viewer	
[C:/Users/cwooters/AppData/Local/Temp/AgPythonReport.dat10636_	41
Local Time: 2019-11-20 10:33:47.096659	·''
UTC Time: 2019-11-20 15:33:47.096659	
Residuals with Bias	
Grouping by ['Tracker Name']	
Grouping by ['Iracker Name']	
Tracker Name: Baseline.COOK-A	
Date Time [UTCG] Satellite Na	
01 Jun 2015 19:46:20.000000 Satellite1 01 Jun 2015 19:46:20.000000 Satellite1	2
01 Jun 2015 19:46:20.000000 Satellite1	
01 Jun 2015 19:46:30.000000 Satellite1	-
01 Jun 2015 19:46:40.000000 Satellite1	
01 Jun 2015 19:46:40.000000 Satellite1	-
01 Jun 2015 19:46:50.000000 Satellite1	Range
01 Jun 2015 19:46:50.000000 Satellite1	Doppler
01 Jun 2015 19:47:00.000000 Satellite1	
01 Jun 2015 19:47:00.000000 Satellite1	
01 Jun 2015 19:47:10.000000 Satellite1	-
01 Jun 2015 19:47:10.000000 Satellite1	
01 Jun 2015 19:47:20.000000 Satellite1 01 Jun 2015 19:47:20.000000 Satellite1	
01 Jun 2015 19:47:20.000000 Satellite1 01 Jun 2015 19:47:30.000000 Satellite1	
01 Jun 2015 19:47:30.000000 Satellite1	- V
	>
	7
J	

- 8. Right-click the Report and select Export to Microsoft Excel. This exports the report data to an Excel spreadsheet.
- 9. Close the report, but leave the scenario open to continue with this exercise.

4.2 Static graphs

NOTE: The activities in this section require the filter output that was generated in the preceding sections. If you have not yet completed those activities, you must do so before proceeding.

Now you will create a static graph on the basis of the output of a completed filter run.

- From the View menu, select the Static Product Builder unless it is already open. If the Static Product Builder is already open, click the sicon to add a new data product to the list on the left side of the window and rename it.
- 2. Click the Inputs tab.

- 3. In the Data Source area, if the *.filrun file that you created earlier is not already loaded, click the Add button, double-click where indicated in the Filename field, and load the file.
- 4. In the Data Limiting area, limit Measurement Type to Range and Tracker Name to REEF-A.
- 5. Select each one and use the right arrow button to move it from the Available list to the Selected list.

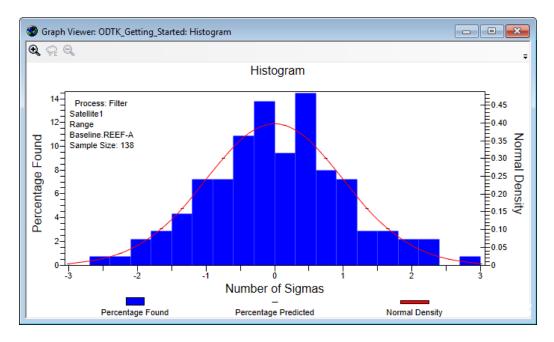
1 61 61 61 51 57 5 7 67					
Products	Data Source	20			
Data Product	Enabled	Objects	Filename	_	Add
	true	click to edit	C:\Users\rmotsay\Documents\ODTK 7\DataArchive\Scenario1.filrun		Remove
	<			>	Remove All
					Kemove All
	- Event - Facility - Facility - Facility - Tracke - Tracke - Ba - Tracke - Tracke - Ba - Tracke - Ba - Tracke - Ba - Tracke	Name rement Type oppler ange e Name e Name seline.COK-A seline.GUAM-A seline.GUAM-A seline.REEF-A ng Strand			

In this exercise, you will create a histogram.

6. Click the Outputs tab and select the Histogram graph style (preceded by the icon $rac{100}{100}$):

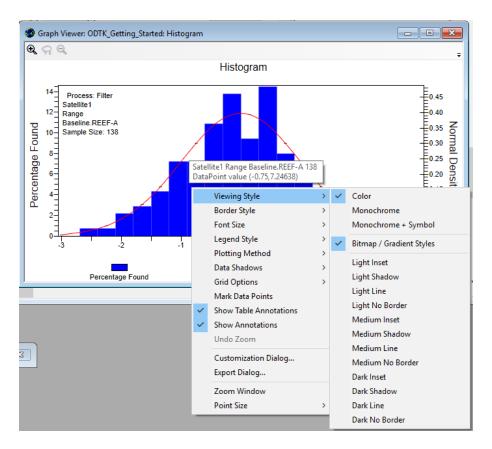
Outputs Inputs Product Sty	les (Graphs and Reports)			
	ies (orapris and iteports)			
勝 FF Pos I 勝 FF SRP 勝 Finite M 勝 Finite M 勝 Finite M 勝 Finite M 勝 Finite M 比 節 Finite M W 節 Finite N W 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	Consistency Janeuver Consistency Jarve Body Thrust States Jarv I nertial Thrust States Jarv Thrust Magnitude and Direction Jarv Thrust Magnitude Pct Jarv Thrust Magnitude Pct Jarv Thrust Magnitude Pct Mar Thrust Magnitude Pct Mar Styles	Hadamard Variance Histogram Summany Instant Maneuver Su Ionosphere Measure Lander Location Cor Lander Location Unc	- Receiver - Satellite / mmary ment Corrections isistency isistency ertainty estimate. It is valid	日本 日本 日本 日本 日本 日本 日本 日本 日本 日本
Export P	roduct		Sing V.	800
		~		
Destination	File		(Pixels) Y:	500
	## FF Pos l ## FF SRP ## Finite N ## Finite N ## Finite N ## Finite N ## Finite N ## Finite N E# Finite N E# Finite N Costion: Edt Description Location: Edt Display F Export Pr Format:	FF Pos Consistency FF SRP Consistency FF SRP Consistency Frinte Maneuver Consistency Finite Mnvr Body Thrust States Finite Mnvr RIC Thrust States Finite Mnvr RIC Thrust Magnitude and Direction Finite Mnvr Thrust Magnitude Pct Finite	FF Pos Consistency Hadamard Variance FF SRP Consistency Histogram Variance Finite Mareuver Consistency Histogram Variance Finite Mareuver Consistency Histogram Variance Finite Mareuver Substrates Histogram Variance Finite Mare RIC Thrust States Instant Maneuver Substrates Finite Mare RIC Thrust Magnitude and Direction Instant Maneuver Substrates Finite Mare Thrust Magnitude Pct Lander Location Core Finite Mare Thrust Magnitude Pct Lander Location Core Finite Mare Thrust Magnitude Pct Lander Location Core Escription: Reports residuals with +/- three-sigma bounds and includes the bias Location: Location: C:\Program Files\AGI\ODTK \AppData\Styles\Static\Residuals Edt Add Graph Display Product Export Product Format: TXT	FF Pos Consistency Hadamard Variance - Receiver FF SRP Consistency Hadamard Variance - Satellite Finite Mareuver Consistency Histogram Finite Mnvr Body Thrust States Histogram Summary Finite Mnvr RIC Thrust States Instant Maneuver Summary Finite Mnvr RIC Thrust Magnitude and Direction Instant Maneuver Summary Finite Mnvr Thrust Magnitude Pct Lander Location Consistency Finite Mnvr Thrust Magnitude Pct and Direction Lander Location Uncertainty Costification Crostification Finite Mnvr Thrust Magnitude Pct Lander Location Uncertainty Event Partice Lander Location Uncertainty Costification Crostification Uncertainty Cation: C:\Program Files\AGI\ODTK \ODTK\AppData\Styles\Static\Residuals_with_Bias.pyrpt Edit Add Graph Display Product Export Product Format: TXT Size

7. Now click the 🖾 (Run Selected) icon:



The graph shows the percentage of range residuals in various sigma intervals compared to a Gaussian (normal) distribution.

8. Right-click the mouse over one of the vertical bars to display a local shortcut menu for that area of the graph:

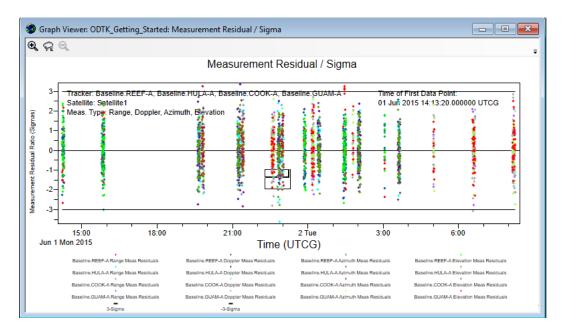


Experiment with some of the various options available; not all options necessarily have an effect.

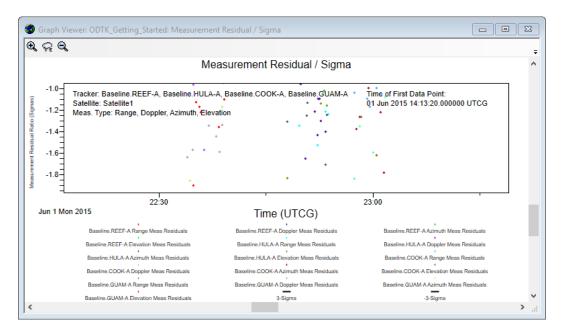
4.3 Graphical residual editing

In this exercise, you will use ODTK's graphical residual editor.

- 1. Return to the Static Product Builder page by clicking the lower tab; click the Outputs tab if necessary.
- 2. Copy the Histogram graph in the Products area and rename it.
- 3. Select the Residual Ratios graph style (preceded by the icon \mathbb{H}).
- 4. Next, click the Inputs tab, and clear the Data Limiting selections by clicking if necessary.
- 5. Now click the 🖾 (Run Selected) icon to generate a graph of residual ratios, which are measurement residuals divided by their standard deviations.
- 6. After the graph appears, click the sicon in the upper left of the graph to display the Selected Points pane.
- 7. Place the cursor on graph. Drag the cursor while holding down the left mouse button to expose the selection cursor ^(h) in order to "lasso" a square region, like this:



8. When you release the left mouse button, the edited points become marked and the selected list fills on the right-hand side, like this:



All measurements associated with the points in this region have now been marked for editing.

- 9. To clear all points, lasso them again. Using the graphical zoom feature can help isolate individual measurements.
- 10. When you are done selecting points, click the Reject button. When you apply your selection, the points will disappear from the Selected Points pane and the markers will disappear from the graph, although the graphed points themselves will not disappear.

- 11. To verify that the points have been applied, double-click the filter object to expose its properties. In the filter's property hierarchy, find Filter → Residual Editing → Schedule, and double-click it. Here you should see additions to the editing schedule created by the graphical editor. The next time you run the filter, ODTK will ignore the measurements identified within the schedule. It is also possible to edit this schedule manually.
- 12. Rerun the filter and generate a new residual-ratios graph. Notice that the result is slightly different than before; this is because different data were used.

This exercise has touched on just a few of many display and formatting options — and on only two of many graph styles — that are available for analysis using ODTK. You can also customize report and graph styles. To do this, click fightharpoondown for the Outputs pane to make a new report or graph style from an existing one. You can also click <math>fightharpoondown for the formatting options and the style formatting options are stored or the style from an existing one. You can also click <math>fightharpoondown for the stored options are stored options.